**ASSIGNMENT 4**

Ultrasonic sensor simulation in Wokwi

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| Date | 25 October 2022 |
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| Maximum Marks | 2 Marks |

**Question-1:**

Write a code and connections in wokwi for the ultrasonic sensor. Whenever the distance is less than 100cms send an “Alert” to IBM cloud and display in the device recent events.

# Code:

#include <WiFi.h> #include <PubSubClient.h>

void callback(char\* subscribetopic, byte\* payload, unsigned int payloadLength);

//-------credentials of IBM Accounts------

#define ORG "kotoq5"//IBM ORGANITION ID

#define DEVICE\_TYPE "ESP32"//Device type mentioned in ibm watson IOT Platform #define DEVICE\_ID "12345"//Device ID mentioned in ibm watson IOT Platform #define TOKEN "12345678" //Token

String data3;

char server[] = ORG ".messaging.internetofthings.ibmcloud.com"; char publishTopic[] = "iot-2/evt/Data/fmt/json";

char subscribetopic[] = "iot-2/cmd/test/fmt/String"; char authMethod[] = "use-token-auth";

char token[] = TOKEN;

char clientId[] = "d:" ORG ":" DEVICE\_TYPE ":" DEVICE\_ID;

WiFiClient wifiClient;

PubSubClient client(server, 1883, callback ,wifiClient); const int trigPin = 5;

const int echoPin = 18; #define SOUND\_SPEED 0.034 long duration;

float distance;

void setup() { Serial.begin(115200); pinMode(trigPin, OUTPUT); pinMode(echoPin, INPUT); wificonnect(); mqttconnect();

}

void loop()

{

digitalWrite(trigPin, LOW); delayMicroseconds(2); digitalWrite(trigPin, HIGH); delayMicroseconds(10); digitalWrite(trigPin, LOW); duration = pulseIn(echoPin, HIGH); distance = duration \* SOUND\_SPEED/2; Serial.print("Distance (cm): "); Serial.println(distance); if(distance<100)

{

Serial.println("ALERT!!"); delay(1000); PublishData(distance); delay(1000);

if (!client.loop()) { mqttconnect();

}

}

delay(1000);

}

void PublishData(float dist) { mqttconnect();

String payload = "{\"Distance\":"; payload += dist;

payload += ",\"ALERT!!\":""\"Distance less than 100cms\""; payload += "}";

Serial.print("Sending payload: "); Serial.println(payload);

if (client.publish(publishTopic, (char\*) payload.c\_str())) { Serial.println("Publish ok");

} else {

Serial.println("Publish failed");

}

}

void mqttconnect() {

if (!client.connected()) { Serial.print("Reconnecting client to "); Serial.println(server);

while (!!!client.connect(clientId, authMethod, token)) { Serial.print(".");

delay(500);

}

initManagedDevice(); Serial.println();

}

}

void wificonnect()

{

Serial.println(); Serial.print("Connecting to "); WiFi.begin("Wokwi-GUEST", "", 6); while (WiFi.status() != WL\_CONNECTED) { delay(500);

Serial.print(".");

}

Serial.println(""); Serial.println("WiFi connected"); Serial.println("IP address: "); Serial.println(WiFi.localIP());

}

void initManagedDevice() {

if (client.subscribe(subscribetopic)) { Serial.println((subscribetopic)); Serial.println("subscribe to cmd OK");

} else {

Serial.println("subscribe to cmd FAILED");

}

}

void callback(char\* subscribetopic, byte\* payload, unsigned int payloadLength)

{

Serial.print("callback invoked for topic: "); Serial.println(subscribetopic);

for (int i = 0; i < payloadLength; i++) {

//Serial.print((char)payload[i]); data3 += (char)payload[i];

}

Serial.println("data: "+ data3);

data3="";

}

# Diagram.json:

{

"version": 1,

"author": "Rithick Kumar ", "editor": "wokwi", "parts": [

{ "type": "wokwi-esp32-devkit-v1", "id": "esp", "top": -4.67, "left": -114.67, "attrs": {} },

{ "type": "wokwi-hc-sr04", "id": "ultrasonic1", "top": 15.96, "left": 89.17, "attrs": {} }

],

"connections": [

[ "esp:TX0", "$serialMonitor:RX", "", [] ],

[ "esp:RX0", "$serialMonitor:TX", "", [] ], [

"esp:VIN", "ultrasonic1:VCC", "red",

[ "h-37.16", "v-178.79", "h200", "v173.33", "h100.67" ]

],

[ "esp:GND.1", "ultrasonic1:GND", "black", [ "h39.87", "v44.04", "h170" ] ],

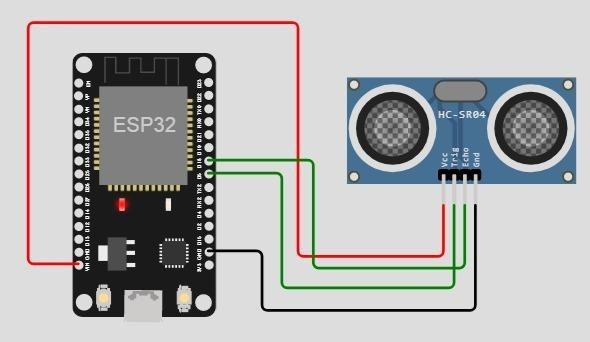
[ "esp:D5", "ultrasonic1:TRIG", "green", [ "h54.54", "v85.07", "h130.67" ] ],

[ "esp:D18", "ultrasonic1:ECHO", "green", [ "h77.87", "v80.01", "h110" ] ]

]

}

# Circuit Diagram:



**Output:**

Wokwi output:

